EECS 388: Computer Systems and Assembly Language Homework 5 Solution

1. (20) How many RTI interrupt events must occur to generate a 15 minute delay assuming the MCLK is operating at 2MHz and the RTR[2:0] bits are set for "110"? How do you set up the Real_Time Interrupt Control Register (RTICTL) (i.e., enable RTI and set RTI pre-scale) for this purpose?

According to the table on page 229 of your textbook, the period of a RTI interrupt is set by the MCLK frequency divided by a divisor stored in RTR[2:0]. Therefore:

- RTR[2:0] = "110" implies a clock divider of 2^{18} .
- MCLK = 2 MHz and a divider of 2^{18} implies that the frequency of RTI interrupts is 7.63 Hz (2 MHz / 2^{18}).
- The time delay, or period, between RTI events is thus 1/7.63 Hz = 0.13 seconds (because period = 1 / frequency).

Now, if we want a delay of 15 minutes:

- 15 minutes = 900 seconds.
- Number of RTI events for 15 minutes =
 - \circ (900 seconds)/(0.13 seconds per delay) = 6,293.08.
 - Thus, it will require about 6,294 RTI events

One must write the appropriate values into the RTICTL in order to enable interrupts and to set the RTI frequency. The RTICTL register is a memory-mapped location located at address \$0014. The RTIE bit is the MSB (bit 7), while the RTR[2:0] bits are the least-significant 3 bits (bits 2 through 0).

RTICTLEQU \$0014; Equate for the address of the RTICTL registerLDAA %10000110; RTICTL mask (RTIE ='1', RTR[2:0] = "110")STAA RTICTL; Store the value into RTICTL

2. (15) Textbook, page 291. Advanced problem #4. Change MCLK to 4 MHz.

Assuming MCLK is at 4 MHz (as stated above), and the pre-scaler is set to 1, this means that the timing frequency is $(4 \text{ MHz})/(2^1) = 2 \text{ MHz}$, or a period of 500 ns.

If the two counts (or timestamps) are \$1993 and \$0C78, then it is obvious that the second "timestamp" is less than the first "timestamp". This means that the clock just happened to rollover during the measurement period, and we must account for this fact in our calculations. This means that the total number of elapsed ticks is:

= (time until rollover) + (time after rollover) =(\$FFFF - \$1993) + (\$0C78 - \$0000) = \$E66C + \$0C78 = \$F2E4 = 62,180 ticks (in decimal)

62,180 ticks * (500 ns / 1 tick) = 31.09 ms

3. (15) Textbook, page 291. Advanced problem #5.

If the period of the pulse being measured is greater than the rollover time fo the counter, then one must make sure to detect counter rollovers in order to accurately measure the signal of interest. Think of this process as noting every New Years Eve from when you were born until the present time in order to figure out how old you are. This requires one to modify the program to log every counter rollover (pulse-accumulator overflow bit, or PAOVF).

Given the numbers from above (problem #2), we know that counter is adjusted by 1 every 500 ns, and that the counter will rollover when it reaches 2¹⁶, or 65,536. This means that pulse length of interest can be found by counting counter rollovers:

Period= # rollovers + # of extra ticks = (500 ns / 1 tick) *[(# of rollovers)*(65,536 ticks / 1 rollover)+ (current ticks)] 4. (25) Write a program to measure the period of a periodic signal connected to input channel 3 by measuring the count difference between two falling edges. Set PR2:PR0 = 011. Use polling method.

This program is very much like the example program found on pg. 273 of the textbook.

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; ; Program Definitions . ************************************			
, REG_BASE TMSK1 TMSK2 TCTL4 TIOS TC3H TSCR TFLG1 TCNT TMSK2_IN TCTL4_IN TIOS_IN	EQU EQU EQU EQU EQU EQU EQU EQU EQU EQU	\$0000 \$8C \$8D \$8B \$80 \$96 \$86 \$8E \$96 \$03 \$C0 \$00	 ; Base address for calculating offsets to other registers ; Offset for TMSK1 register ; Offset for TMSK2 register ; Offset for TCTL4 register ; Offset for TC3H register ; Offset for TSCR register ; Offset for TFLG1 register ; Offset for TCNT register ; Set the pre-scale bits ; Configure falling edges ; Select channel 3 for input compare
TSCR_IN CLR_CH3	EQU EQU	\$80 \$08	; Enable timer ; Mask to clear channel 3 flag
; Data section ORG \$6000 edge1 FDB \$0000 ; Reserve a word (16-bits) for edge measurement			
period	FDB	\$0000 \$0000	; Reserve a word (16-bits) for period measurement
; Code section ORG \$4000 LDS #\$8000 ; Initialize the stack pointer JSR TIMERINIT ; Initialize the timer JSR MEASURE ; Measure the period			
DONE BRA DONE ; Infinitely loop to halt program			

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; Function used to enable timer subsystem
TIMERINIT
      CLR TMSK1
                  ; disable interrupts
      LDX #REG_BASE
                          ; Load X with base address of registers
      LDAA #TMSK2_IN
                           ; Set pre-scale
      STAA TMSSK2, X
      LDAA #TCTL4_IN
                           ; Configure for falling edges
      STAA TCTL4, X
      LDAA #TIOS_IN
                           ; Select channel 3
      STAA TIOS_IN, X
      LDAA #TSCR_IN
                           ; Enable timer
      STAA TSCR_IN, X
      RTS
             ; return
; Function used to measure signal period
; via polling method
                *****
MEASURE
                          ; Clear channel 3 flag to prepare measurements
      LDAA #CLR_CH3
      STAA TFLG1,X
      ; Grab measurement of first edge
WAIT1
      BRCLR TFLG1,X,$08,WTFLG
                                 ; Wait for an edge
      LDD TCNT,X
                                 ; Load in counter value
                                 ; Save the measurement
      STD edge1
      LDAA #CLR_CH3
                                 ; Clear channel 3 flag again
      STAA TFLG1,X
      ; Grab measurement of second edge
WAIT2
      BRCLR TFLG1,X,$08,WTFLG
                                 ; Wait for an edge
      LDD TCNT,X
                                 ; Load in counter value
      SUBD edge1
                                  ; Calculate the difference between edges
                                 ; Store the period result
      STD period
      RTS
             ; return
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5. (25) Generate a 1500Hz square wave with a 40% duty cycle (ON/PERIOD) on output compare channel 2 (OC2). MCLK = 8MHz. Set the pre-scaler to divide by 4. Use interrupt.

This program is very much like the example program found on pg. 275 of the textbook. If the MCLK runs at 8 MHz and the pre-scaler is set to 4, then the counter will adjust at a rate of (8 MHz)/4 = 2 Mhz, or with a period of 500 ns.

A 1500 Hz signal has a period of 666.67 microseconds, and a 40% duty cycle means that it will be high for 0.4*666.67 microseconds or 266.67 microseconds, and low for 400 microseconds. This translates to counter value of:

High counter:

= 266.67 microseconds * (1 tick / 0.5 microseconds) = 534 ticks \rightarrow \$0216 Low counter: = 400 microseconds * (1 tick / 0.5 microseconds) = 800 ticks \rightarrow \$0320

The program on p. 275 can be modified to perform the 40% duty cycle switch by changing the following:

- TMSK2_IN needs to be changed to \$04
 - This sets the correct pre-scale for our problem.
 - Pre-scale of 4 $(2^2 = 4)$.
- The first instance of #\$03E8 (in TIMERINIT) needs to be changed to the counter value for our high counter, or #\$0216.
- The instance of #\$03E8 (in SQWAVE) needs to be changed to alternate between the high and low-counter values using a conditional branch to implement an IF statement.
 - This can be easily done by reserving a word (double-byte) in memory to contain the count value. This value will "flip-flop" between the high and low counter value during every iteration of the loop (see the following modifications.

****** ; New data section ***** ORG \$6000 FDB \$0000 ; Location to hold counter increment COUNT_INC <Within TIMERINIT> ; Initialize COUNT INC to be low counter value LDD \$0320 STD COUNT_INC <Replace SQWAVE with the following> SOŴAVE BRCLR TFLG1,\$04,SQWAVE ; Poll for counter flag LDD TC2H ; Load in counter value LDX COUNT INC ; Load in current COUNT INC CPX #\$0216 ; Compare to high-count BEQ ADD_LOW ; If high \rightarrow add low ADDD #\$0216 ; Otherwise, add high LDX #\$0216 ; Update COUNT_INC STX COUNT INC BRA ENDIF ADD LOW ADDD #\$0320 ; Add low LDX #\$0320 ; Update COUNT_INC STX COUNT_INC **ENDIF** STD TC2H ; Setup next transition time JSR CLEARFLAG; generate repetitive signal RTS ; return